







One twisted wire pair

85 mW

### **FEATURES**

- INOVA's single component digital sensor
- Patented MEMS accelerometer and custom electronics to record P-wave
- Single-point receivers with one or three individual sensors per string
- Smallest and most compact digital sensor on the
- Offers flat amplitude and phase response over a wide frequency range
- Insensitivity to tilt-degradation enables faster deployment of sensors in comparison to geophones
- Robust mechanical housing to withstand operational and environmental stresses
- Compatible with INOVA's Hawk® and G3i® HD acquisition systems



# **TECHNICAL SPECIFICATIONS**

Frequency Response: DC to 400 Hz 24 Bits (23 + Sign) Digital Quantization:

Sample Rate: 4 ms, 2 ms, 1 ms, 0.5 ms Low-Cut Filter Options: 3 Hz,1.45 Hz,Out

Time Standard: Phase locked to acquisition system Digital High-Cut Filter: 0.82 Nyquist

clock

Normal Mode: 0.3 µm/s<sup>2</sup>/VHz

Full Scale (peak) Normal Mode: 3.3 m/s<sup>2</sup> (335mG) Total Harmonic Distortion: < -100 dB

Large Signal Mode: 4.9 m/s<sup>2</sup>

(500mG)

Noise<sup>[1]</sup>

Sensor Module Interface:

Power Consumption [1]:

[30nG/VHz]

3 Hz to 400 Hz

Dynamic Range [1][2] Normal Mode: 118 dB

Frequency Response: DC to 400 Hz

Low-Cut Filter Options: 3 Hz,1.45 Hz,Out

Digital High-Cut Filter: 0.82 Nyquist

Total Harmonic

< -100 dBDistortion:



## **PHYSICAL SPECIFICATIONS**

6.93 cm (H), 6.47 cm (Ø) Dimensions:

2.73 in (H)), (2.55 in (Ø))

216.96 cc [13.24 cu in] Volume:

200 q (0.441 lb) Weight:

# **ENVIRONMENTAL SPECIFICATIONS**

Operating Temperature: -40 °C to +75 °C

Storage Temperature: -50 °C to +85 °C

Shock: 1500 q, ½ ms, ½ sine

Humidity: 0% to 100% RH non-condensing

Water Depth Rating: 5 m

#### **TESTING**

Embedded Power-up Self Test: Sensor wake-up and self configuration checks

Operator Controlled System Tests: Spread noise

Sensor loopback (verifies module telemetry, digital filter performance

and sensor functionality)

Telemetry error count

Sensor Tilt

Sensor Status Checks: Overscale status

Sensor offset

Digital fault flags