## VectorSeis® digital sensors



## **VECTORSEIS ML21/MT21**

### **FEATURES**

- INOVA's industry-leading multicomponent, digital sensor
- Patented MEMS accelerometers to record X, Y, and Z data
- Enables measurement of true ground motion by recording the full seismic wavefield
- Compatible with INOVA's G3i® HD and Hawk® acquisition systems
- Single-point receivers to facilitate the imaging of anisotropic reservoirs
- Tilt-insensitivity enables faster deployment of sensors in comparison to geophone arrays
- Reinforced with a more robust and rugged mechanical housing, including a 60% stronger case to withstand operational and environmental wear and tear
- 20% power consumption improvement over first generation VectorSeis
- Response down to DC by deselecting low-cut filters
- New MT21 design supports marsh applications

#### **TECHNICAL SPECIFICATIONS**

Digital Quantization:	24 Bits (23 + Sign)		
Sample Rate:	4 ms, 2 ms or 1 ms 0.5 ms with compatible systems		
Time Standard:	Phase locked to acquisition system clock		
Full Scale (peak) (Normal Mode):	+/- 3.3 m/s² (at all inclinations)		
(Strong Motion Mode):	+/- 13.1m/s <sup>2</sup> (source radius enabled with compatible systems; at all inclinations including gravity and offset)		
Noise (Normal Mode):	0.4 µm/s²/√Hz 3 Hz to 375 Hz		
Equivalent Input Noise (EII	N)		
(Normal Mode):	4.18 μm/s² @ 4 ms 5.95 μm/s² @ 2 ms 8.46 μm/s² @ 1 ms 3 Hz to ¾ Nyquist		
Instantaneous Dynamic Ra (Normal Mode):	<b>nge</b> 118 dB @ 4 ms 115 dB @ 2 ms 112 dB @ 1 ms		

3 Hz to <sup>3</sup>/<sub>4</sub> Nyquist (at all inclinations)

Technical specifications are typical values at 25°C









## **VECTORSEIS ML21/MT21**

### **TECHNICAL SPECIFICATIONS**

Total System		PHYSICAL			
Dynamic Range:	130 dB @ 4 ms	<b>Dimensions:</b>	Dimensions:		
	127 dB @ 2 ms	Body:	16.87 cr	n x 5.49 cm diameter	
	124 dB @ 1 ms	,			
	3 Hz to ¾ Nyquist (at all inclinations)	Top (ML21):	3.55 cm	with an OD of 7.68 cm	
Frequency Response:	Linear or minimum phase response				
	–128 dB attenuation behind Nyquist	Top (MT21): 3.58 cm w		vith an OD of 7.62 cm	
	Pass-band Ripple +/- 0.1 dB				
	93.8 Hz @ 4 ms	<b>Weight:</b> 0.771 kg, i		g, including 2 m cable and connector	
	187.5 Hz @ 2 ms				
	375 Hz @ 1 ms				
Digital Low-Cut Filter:	None or choice of 32 frequencies from				
	3 to 90 Hz, 12 dB/octave	ENVIRONMENTAL			
		<b>Operating Tempe</b>	rature:	-40 °C to +75 °C	
Digital Offset Filter:	(i) Continuous Filter				
	1.450 Hz @ 4 ms	Humidity:		0 to 100%	
	1.463 Hz @ 2 ms	-			
	1.470 Hz @ 1 ms	Operating Altitude:		-100  m to $+5500  m$	
	6 dB/octave	operating Autouc.			
	(11) Fixed DC Offset Removal	Watan Danth Dati		15	
		water Depth Rati	ng:	15 M	
Total Harmonic Distortion:	<0.002%*				
Sensor to Sensor Matching:	+/- 0.4% (at all inclinations)				
Cross Axis Isolation:	- 46 dB				

**Sensor Module Interface:** Proprietary 2-wire interface

**Inclination Resolution:** +/- 0.5° arc (relative to vertical)

\*Measurement limited by mechanical test apparatus. Technical specifications are typical values at 25°C



# VectorSeis® digital sensors



## **VECTORSEIS ML21/MT21**

### **RELATED PRODUCTS**

Alignment Tool: For aligning all VectorSeis receivers along survey specific azimuth during deployment





For extracting VectorSeis receivers from the ground

Extraction Tool:

#### TESTING

Embedded Power-up Self Test:	Sensor wake-up and self configuration checks		
	Control loop validation		
Operator Controlled System Tests:	Vertical orientation (evaluates each sensor axis gravity magnitude and vector sum of all 3 sensors) Spread noise		
	Sensor loopback (verifies module telemetry and digital filter performance)		
	Telemetry error count		
End of Record Validation Tests			
(Every Record):	Overscale status		
	Vertical orientation (used to apply orientation correction)		
	Sensor orientation deviation (evaluates orientation after each acquisition)		
	Sensor offset		
	Digital fault flags		





### **RESPONSE CURVES**











