# **Vectorseis® Digital Sensors**



## **VECTORSEIS ML21/MT21**

#### **FEATURES**

- INOVA's industry-leading multicomponent, digital sensor
- Patented MEMS accelerometers to record X, Y, and Z data
- Enables measurement of true ground motion by recording the full seismic wavefield
- Compatible with INOVA's G3i<sup>®</sup> HD and Hawk<sup>®</sup> acquisition systems
- Single-point receivers to facilitate the imaging of anisotropic reservoirs
- Tilt-insensitivity enables faster deployment of sensors in comparison to geophone arrays
- Reinforced with a more robust and rugged mechanical housing, including a 60% stronger case to withstand operational and environmental wear and tear
- 20% power consumption improvement over first generation VectorSeis
- Response down to DC by deselecting low-cut filters
- MT21 design supports marsh applications



**ML21** 

## **TECHNICAL SPECIFICATIONS**

Digital Quantization:	24 Bits (23 + Sign)	
Sample Rate:	4 ms, 2 ms or 1 ms 0.5 ms with compatible systems	
Time Standard:	Phase locked to acquisition system clock	
Full Scale (peak) (Normal Mode):	+/- 3.3 m/s <sup>2</sup> (at all inclinations)	
(Strong Motion Mode): systems;	+/- 13.1m/s² (source radius enabled with compatible	
	at all inclinations including gravity and offset)	
Noise (Normal Mode):	0.4 µm/s²/√Hz 3 Hz to 375 Hz	
Equivalent Input Noise (EIN)		
(Normal Mode):	4.18 μm/s <sup>2</sup> @ 4 ms 5.95 μm/s <sup>2</sup> @ 2 ms 8.46 μm/s <sup>2</sup> @ 1 ms 3 Hz to ¾ Nyquist	
Instantaneous Dynamic Ran (Normal Mode):	<b>nge</b> 118 dB @ 4 ms 115 dB @ 2 ms 112 dB @ 1 ms	

Technical specifications are typical values at 25°C



MT21

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#### **TECHNICAL SPECIFICATIONS**

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Total System		H
Dynamic Range:	130 dB @ 4 ms	
	127 dB @ 2 ms	
	124 dB @ 1 ms	]
	3 Hz to ¾ Nyquist (at all inclinations)	
		]
Frequency Response:	Linear or minimum phase response	
J. J. I.	–128 dB attenuation behind Nyquist	,
	Pass-band Ripple +/- 0.1 dB	1
	93 8 Hz @ 4 ms	
	187 5 Hz @ 2 ms	
	275 Uz @ 1 mg	
	575 HZ @ 1 HIS	
Digital Low Cut Filtor	None or choice of 22 frequencies from	
Digital Low-Gut Fitter:		(
	3 to 90 Hz, 12 dB/ octave	
D'		1
Digital Offset Filter:	(1) Continuous Filter	
	1.450 Hz @ 4 ms	
	1.463 Hz @ 2 ms	(
	1.470 Hz @ 1 ms	
	6 dB/octave	١
	(ii) Fixed DC Offset Removal	

#### PHYSICAL

Dimensions:	
Body:	16.87 cm x 5.49 cm diameter
Top (ML21):	3.55 cm with an OD of 7.68 cm
Top (MT21):	3.58 cm with an OD of 7.62 cm
Weight:	0.771 kg, including 2 m cable and connector

#### **ENVIRONMENTAL**

Operating Temperature:	-40 °C to +75 °C
Humidity:	0 to 100%
Operating Altitude:	-100 m to +5500 m
Water Depth Rating:	15 m

#### **Total Harmonic Distortion:** < 0.002%\*

- **Sensor to Sensor Matching:** +/- 0.4% (at all inclinations)
- Cross Axis Isolation: 46 dB
- Sensor Module Interface: Proprietary 2-wire interface
- **Inclination Resolution:** +/- 0.5° arc (relative to vertical)

\*Measurement limited by mechanical test apparatus. Technical specifications are typical values at 25°C



# **VECTORSEIS ML21/MT21**

#### **RELATED PRODUCTS**

**Alignment Tool:** For aligning all VectorSeis receivers along survey specific azimuth during deployment





**Extraction Tool:** For extracting VectorSeis receivers from the ground

#### TESTING

Embedded Power-up Self Test:	Sensor wake-up and self configuration checks Control loop validation
Operator Controlled System Tests:	Vertical orientation (evaluates each sensor axis gravity magnitude and vector sum of all 3 sensors) Spread noise Sensor loopback (verifies module telemetry and digital filter performance) Telemetry error count
End of Record Validation Tests	
(Every Record):	Overscale status Vertical orientation (used to apply orientation correction) Sensor orientation deviation (evaluates orientation after each acquisition) Sensor offset Digital fault flags



### **RESPONSE CURVES**



80

Time, ms

60

100

20

40

0.1

0.2 0

20

40